

ABSOLUTE ROTARY ENCODER WITH CANOPEN INTERFACE







Chapter1 Connections

1.1 Setup

- 1.1.1 Connect the encoder to Power Supply of 10-30 VDC.
- 2 1.1.2 Connect cable pins to the terminal block.
- 2 1.1.3 Plug the terminal block into the PCAN-USB module.
- 1.1.4 Plug the USB port to a PC.
- > 1.1.5 Place a 100 Ω resistance between CAN_H & CAN_L.
- 1.1.6 Install an interface software in PC that supports PCAN-USB.





2 1.2 Pin Assignment

- 2 1.2.1 White pin to power supply '+'. It is the power supply of the encoder.
- 1.2.2 Blue pin to power supply '-'. It is the GND of the encoder.
- 1.2.3 Grey pin to terminal 2 of the block. It is CAN_L.
- 1.2.4 Brown pin to terminal 3 of the block. It is CAN_GND.
- 2 1.2.5 Black pin to terminal 7 of the block. It is CAN_H.





Chapter2 Configuration

- 2.1 Start Up
- 2.1.1 Open the terminal software: 'PcanView.exe'.



- 2.1.2 The initial figure, 'Connect' window.
 - It recognizes the port automatically.
 - 2. Choose the 'Bit rate'. Default 125 kBit/s.
 - 3. Switch the Filter settings to Standard.
 - 4. Press 'OK' to connect and start configuration.

4 Connect						
PCAN-View						
Available CAN hardware:						
PCAN-USB: Device Bh, Firmware 2.8						
Bit rate: 125 kBit/s Bus timing register value (Hex): 031C						
Filter settings						
3 Standard From: 000 (Hex) To: 7FF (Hex)						
© Extended						
4 OK Cancel 🕃 <u>H</u> elp						



- 2.1.3 PCAN-View Interface Introduction
 - 2 1. Click on the button to pop up the 'Connect' window. (Ctrl+B)
 - 2. Click on the button to pop up the 'New Message' window. (Ins)
 - 3. Received messages are displayed in the 'Receive' column.
 - 2 4. It is the boot up message of the encoder.
 - 5. Commands are displayed in the 'Transmit' column.
 - 6. Shows that the encoder is connected at the Baud rate of 125 kBit/s.

	PCAN-View						x
÷ <u>F</u>	Eile CAN 1 Edit 2 Transmit View Trace Help						
i 😂 - 🛃 👍 + 🔁 🛃 X 🖒 🖒 I 👄 💷 💷 I 🛷 🕦							
Trace 🛱 PCAN-USB							
	Message	DLC	Data		Cycle Time	Count	
a	701h	1	00			1	
Recei	S S S S S S S S S S S S S S S S S S S						
	Message	DLC	Data	Cycle T.	. Count	Trigger	Co
Ę	601h	8	40 00 20 00 00 00 00 00	100	0		-
Ĕ	601h	8	22 03 60 00 FF FF FF 00	100	0		
Ĕ	601h	8	22 10 10 01 73 61 76 65	100	0		
5	601h 0	8 6	40 03 60 00 00 00 00 00	100	0		
● Connected to PCAN-USB (125 kBit/s) 🚔 Overruns: 0 QXmtFull: 0							



- 2.1.4 The 'New Transmit Message' window introduction
 - ▶ 1. Type in '600 + NN'. E.g. 'NN=1', type in '601', which means '601h'.
 - 2. DLC: means digital length, range 0~8.
 - 3. Data: 2 bits each digital in Hex.
 - 4. Cycle Time: type in figure, unit 'ms'. E.g. '100ms' means 10 times in 1 second.
 - 5. Click on to pause message transmitting.
 - 6. Click to add the message into the 'Transmit' column.

New Transmit Message						
ID (Hex): 1 000 DLC: 2 8 ♥	<u>D</u> ata: (Hex) <mark>3</mark> 00 00 00 00 00 00 00 00					
Cycle Time: 4 0 ms	Message Type Extended Frame Remote Request					
C <u>o</u> mmen						
6 OK Cancel 🖓 <u>H</u> elp						







- > 2.2.1 Bit 0
 - 1. '40': Read commands.
 - 2. '22': Write commands.
- > 2.2.2 Bit 1 & 2
 - 2000h: Read Position Value. Bit 0: 40. Bit 1: 00. Bit 2: 20. (Same function with '6004h')
 - 2101h: Read Resolution Per Revolution. Bit 0: 40. Bit 1: 01. Bit 2: 21.
 - 2102h: Read Total Resolution. Bit 0: 40. Bit 1: 02. Bit 2: 21.
 - **50Bh: Read Serial Number. Bit 0: 40. Bit 1: 0B. Bit 2: 65.**
 - 6003h: Read Preset Value. Bit 0: 40. Bit 1: 03. Bit 2: 60.
 - 3000h: Change Node Number. Bit 0: 22. Bit 1: 00. Bit 2: 30. Bit 4: NN.
 - > 3001h: Change Baud Rates. Bit 0: 22. Bit 1: 01. Bit 2: 30. Bit 4: BR.
 - 2300h: Save. Bit 0 ~7: 22 00 23 00 55 AA AA 55



2.3 Receive Message

2.3.1 Resolution Per Revolution

43 01 21 00 00 10 00 00

Bit 4 ~ Bit 7 are the message, '00 10 00 00'. You should read in big Endian. It is '00 00 10 00' in Hex, also '10 00' in Hex. Equals '4096' in Dec, also '2^12'.

2.3.2 Total Resolution

43 02 21 00 00 00 00 01

Bit 4 ~ Bit 7 are the message, '00 00 00 01'. You should read in big Endian. It is '01 00 00 00' in Hex, also '1 00 00 00' in Hex. Equals '4096*4096' in Dec, also ' $(2^{12})(2^{12})$ ', Resolution*Revolution.

2.3.3 Position Value

43 00 20 00 80 DE FF 00

Bit 4 ~ Bit 7 are the message, '80 DE FF 00'. You should read in big Endian. It is '00 FF DE 80' in Hex, also 'FF DE 80' in Hex. Equals 16764928 in Dec, also 4093*4096. The exact position is calculated: 360° /4096*4093=359.74° So the position value is: 359.74° at 4096 round.



2.4 Programmable Parameters

- > 2.4.1 Preset Function
- Preset function enables to set any position as the initial position. Input message of the preset value in the red block, range from '00 00 00 00' to 'FF FF FF 00' in big Endian.



- > 2.4.2 Change Node Number
 - Input the message of Change Node Number like below. Type in the NN you want to change to in the red block in Hex. E.g. '00h' means NN=00+01=01 in decimal. And save after change.

8

22 01 30 00 03 00 00 00



> 2.4.3 Change Baud Rate

30

00 03

00 00 00

Data: (Hex)

22 01

Input the message of Change Baud Rate like below. Type in the BR code of the specific baud rate you want to change to in the red block in Hex. See table on the right. And please save after change.

601h

Baudrate III KBIUS	Буге
20	00h
50	01h
100	02h
125	03h
250	04h
500	05h
800	06h
1000	07h

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Chapter3 Tips

- 3.1 Please save after programmable parameters changed with the command of 2300h.
- 3.2 Please re-power the encoder after new baud rate set and node number changed.
- > 3.3 Please re-connect in the software after the encoder restarted.
- > 3.4 Messages are required in big Endian.
- > 3.5 Read the position value and other data in big Endian.
- > 3.6 Check the baud rate, if the bus is active but no boot up message.
- 3.7 Start-operational mode and Pre-operational mode, please refer to the <u>Manual</u>, on page 10.





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